



# Forth and C on the Cortex-M3

# Arm Cortex-M3

- ◆ 32-Bit Architecture
- ◆ Low-latency Prioritized Interrupt controller - NVIC
- ◆ Single-Cycle Multiply
- ◆ Sophisticated Debug
- ◆ C and Assembly friendly
- ◆ Common across all major Micro-controller vendors
- ◆ Available in Simplified (M0) and Enhanced (M4)

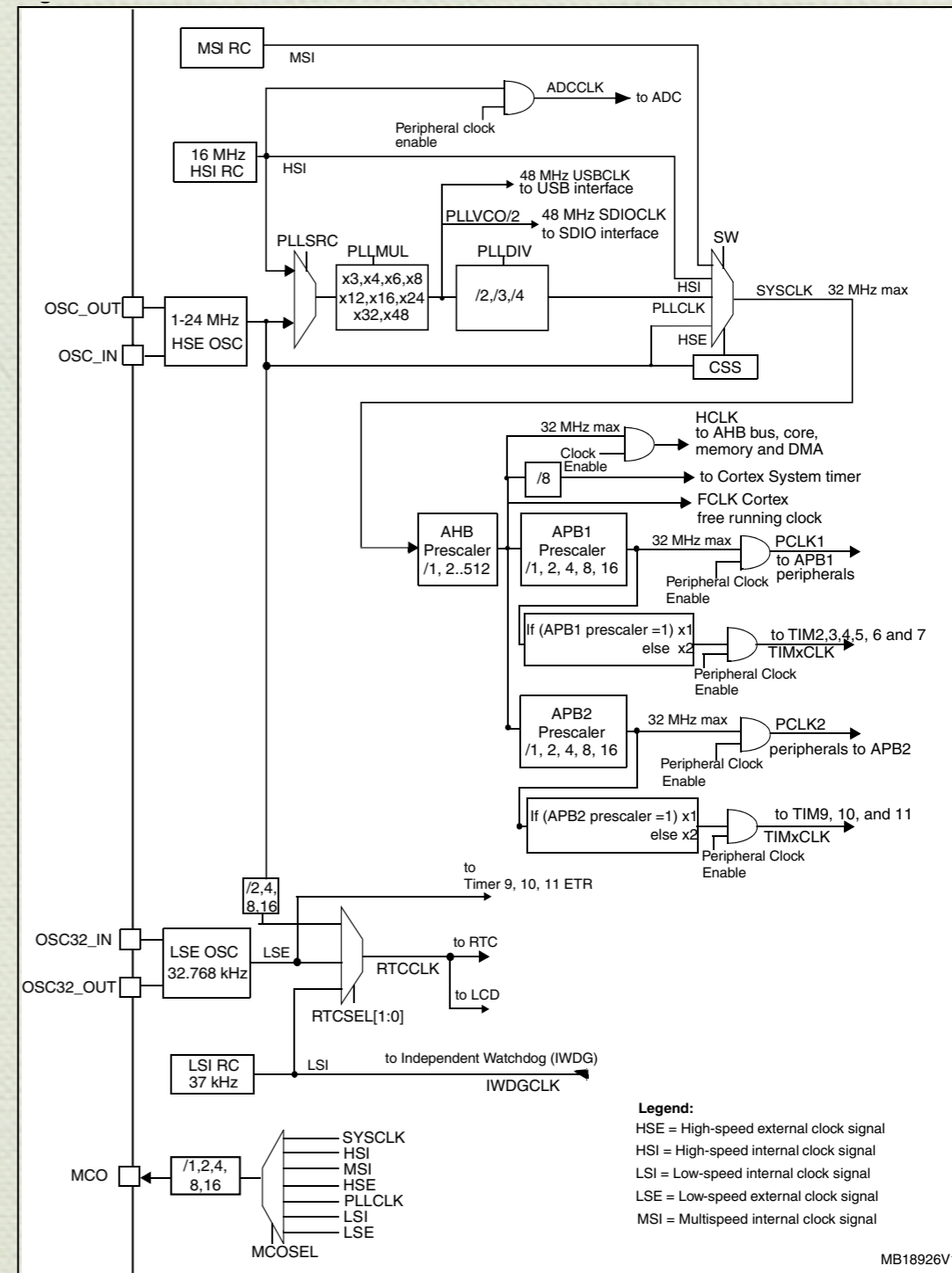
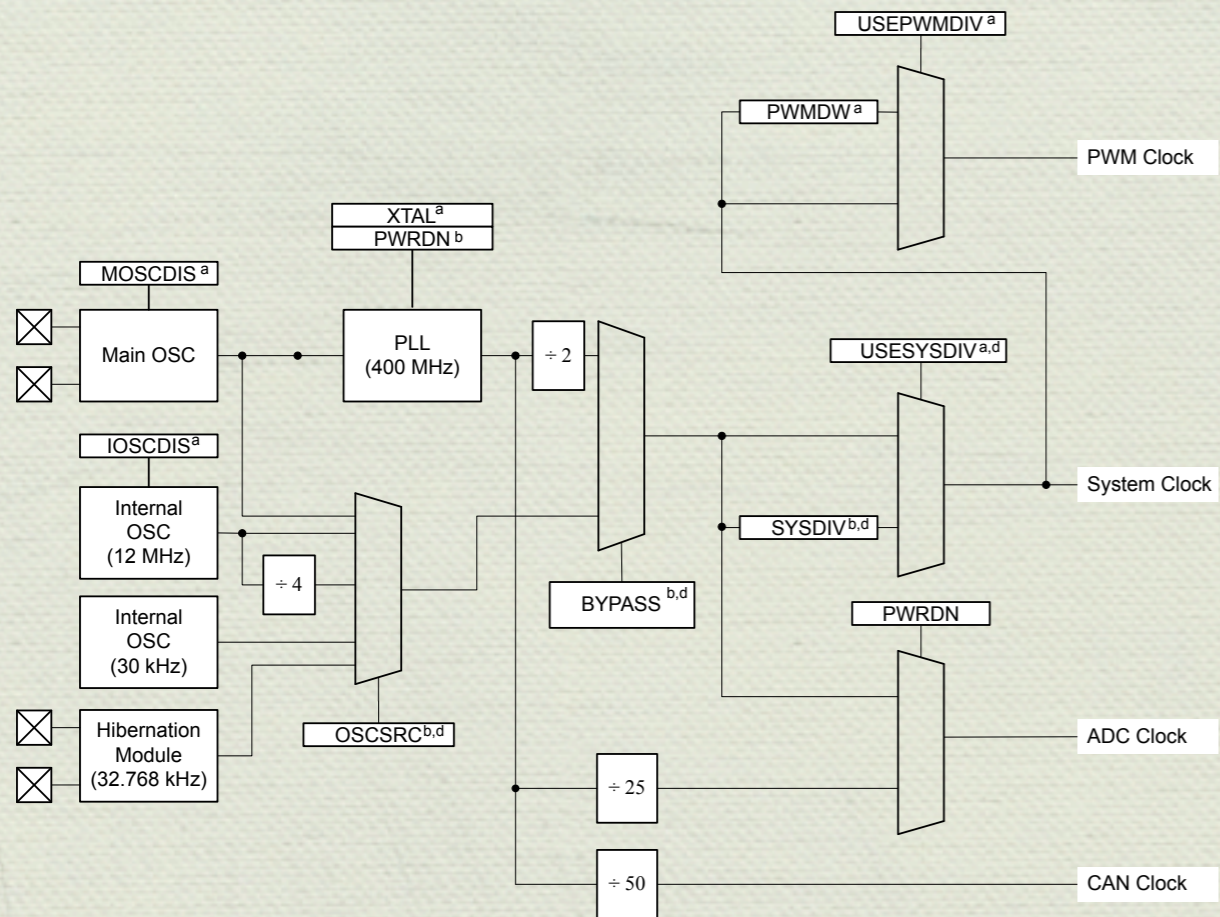
# State of Forth on the M3

- ◆ Plenty of Forths for ARM
- ◆ Cortex-M3 is Thumb-2 - Few off the shelf implementations
  - ◆ Riscy Pygness Forth - Umbilical
  - ◆ MPE Forth - Commercial
- ◆ Machine Initialization varies widely across vendors

# Options for Forth

- ◆ Port Riscy Pygness to a new flavor of M3
  - ◆ Strip out machine init code, and call from C
  - ◆ `main() { ..... ; asm("b initForth"); }`
- ◆ Port HForth or similar direct-threaded Forths
  - ◆ Rely heavily upon assembler macros
- ◆ Commercial Forth

# Clock Trees!



# Bootstrapping the M3

- ◆ Complex Initialization / Reconfiguration
- ◆ Large body of demonstration / reusable code
- ◆ Re-Implementation in Forth is a bad option
  - ◆ Opportunities for Error
  - ◆ Time is best spent on Application Development

# Existing Vendor Code

## ◆ TI StellarisWare

◆ SysCtlClockSet() - 177 Lines of Code

◆ ADCSequenceStepConfigure() - 90 Lines of Code

## ◆ ST Micro Driverlib

◆ SetSysClock() - 82 Lines of Code

◆ ADC\_Init() - 52 Lines of Code

Code that's rich in bit-whacking and specific rules

# Partitioning

**Application Layer**  
31k Flash/12k Ram

Application Development  
Control Interface  
Debugging / Bringup

**System Services - 13k/4k**

USB CDC Services  
Timing Services  
Frame Buffer

**DFU Boot loader - 8.5k/0k**

Inactive after initial boot



# System Call Interface

- ◆ Minimal System Call Support:
  - ◆ API Version
  - ◆ getchar, putchar
  - ◆ get shared variables list
  - ◆ set power state
  - ◆ get current value of millisecond counter

# Forth SVC Calls

```
\ ****  
\ SVC 0: Return the version of the API in use.  
\ ****  
CODE API-Version ( -- n )  
  svc #0 ( Call Supervisor )  
  str tos, [ psp, # -4 ] ! ( Push TOS )  
  mov tos, r0 ( return value )  
  next,  
END-CODE
```

Note: Cortex-M3 Pushes R0-R4, R12, LR, PC, xPSR automatically

# Catching it!

Handler Looks up the SVC Number  
and jumps via table to the right function:

```
// Return an API Version  
void __SAPI_Version(long *frame) {  
    frame[0] = 0x0201;  
    return;  
}
```

R0
R1
R2
R3
R12
LR
PC
xPSR

# Handler-Thread Sync

- ◆ Interrupt handlers need to send 'Events' to each other and to the Thread-Mode tasks.
- ◆ Unidirectional events makes this safe:
  - ◆ ISR: `notify_1Hz = 1;`
  - ◆ Thread resets the event register and waits for change:
    - ◆ `0 notify_1Hz !`
    - ◆ `notify_1Hz @ if <something> then`

# TCB status byte

Bit	When set	When Reset
0	Task is running	Task is halted
1	Message pending but not read	No messages
2	Event triggered	No events
3	Event handler has been run	No events (reset by user)
4..	User defined	User defined

- ◆ Scheduler uses non-zero value to trigger task execution or event handler
- ◆ ISR can set the event bit to trigger task execution
- ◆ Scheduler calls event handler then the task

# Hooking it into a Thread

```
: update-hue-out ( -- )
  stop
  begin
    rtc @ calc_hue rtc2hue_out !
    pause
  again
;

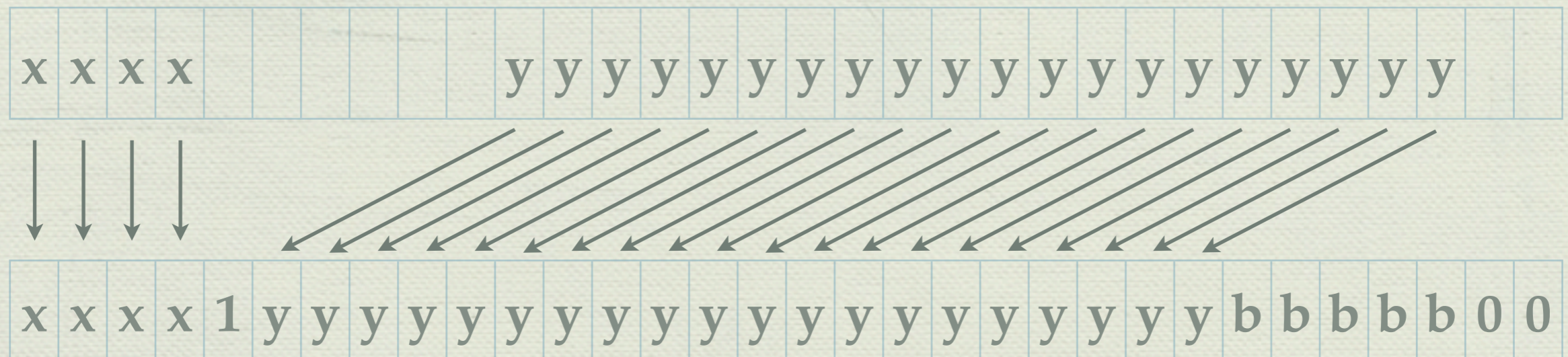
task clock2huetask

: launch-tasks
  ['] clr-event-run clock2huetask to-event
  ['] update-hue-out clock2huetask initiate
;
```

# Bit-Banding on the M3

Atomic!

Target Address -> Bit Band Alias Transformation



Bit  
Number

# Lock-Avoidance

- ◆ Bit-Banding eliminates interrupt lockout
  - ◆ Fewer hazards
  - ◆ Similar instruction count
  - ◆ add an extra word to the TCB
- ◆ 

```
if (notify_refresh_bbp != 0) { *notify_refresh_bbp = 1; }
```
- ◆ 

```
: clr-event-run \ --  
\ * Reset the current task's EVENT_RUN flag.  
0 up@ tcb.bbstatus @ evt-bit# + ! ;
```



# Dynamic Linking

- ◆ Linker places C variables where it sees fit
- ◆ Manually updating pre-defined constants is error-prone
- ◆ Table-Driven approach allows automatic updates

```
runtimelink_t dynamiclinks[] = {  
  { (int*) sizeof(runtimelink_t), sizeof("RECORDLE"), "RECORDLEN", 0, 0},  
  { (int*) hsv_in,      sizeof("hsv_i"),  "hsv_in",  sizeof(uint32_t), 3 } };
```

The address of this array is available via system call.  
Names are encoded as counted strings

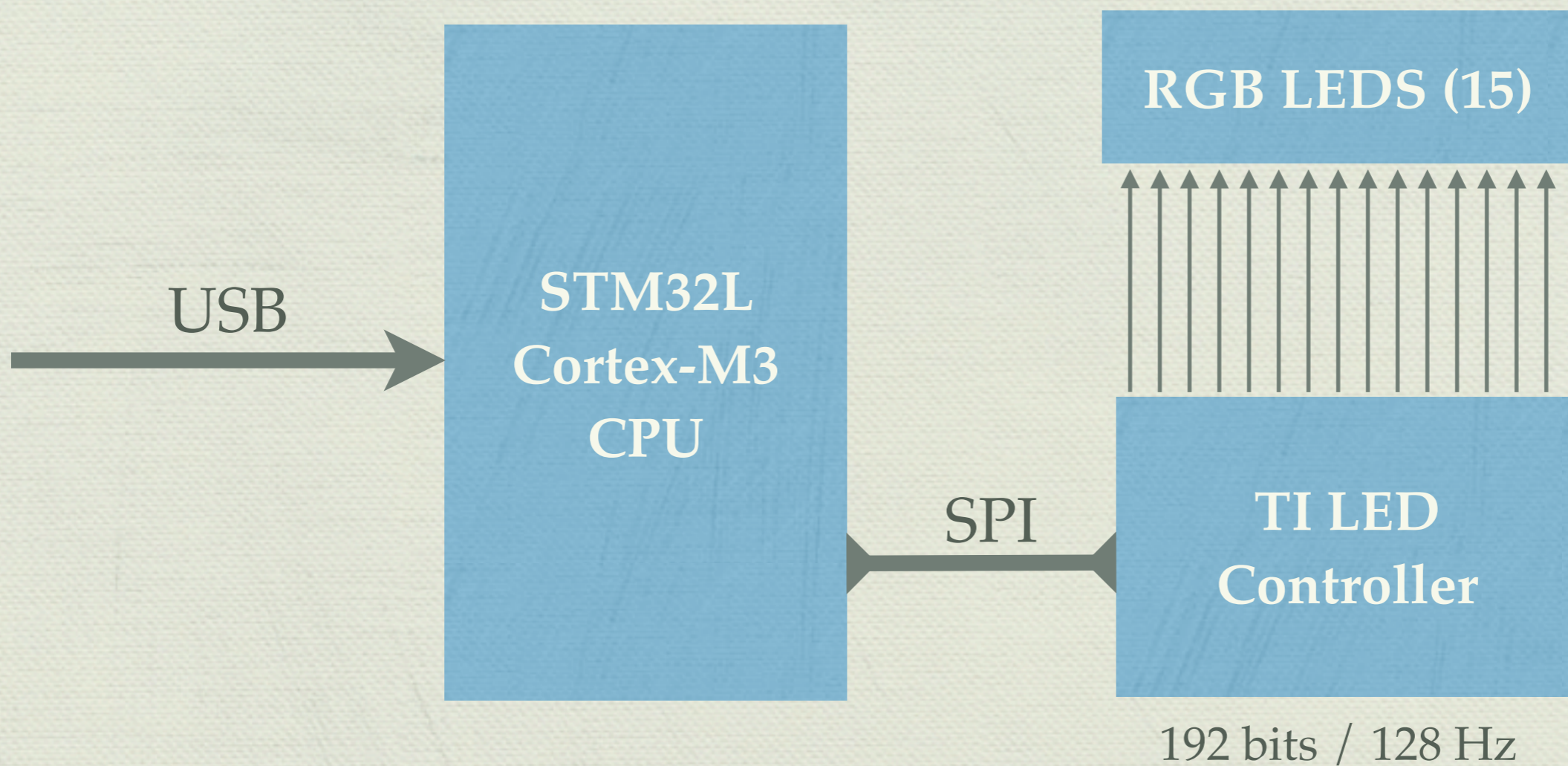
# Questions?

<http://www.kudra.com/forth>

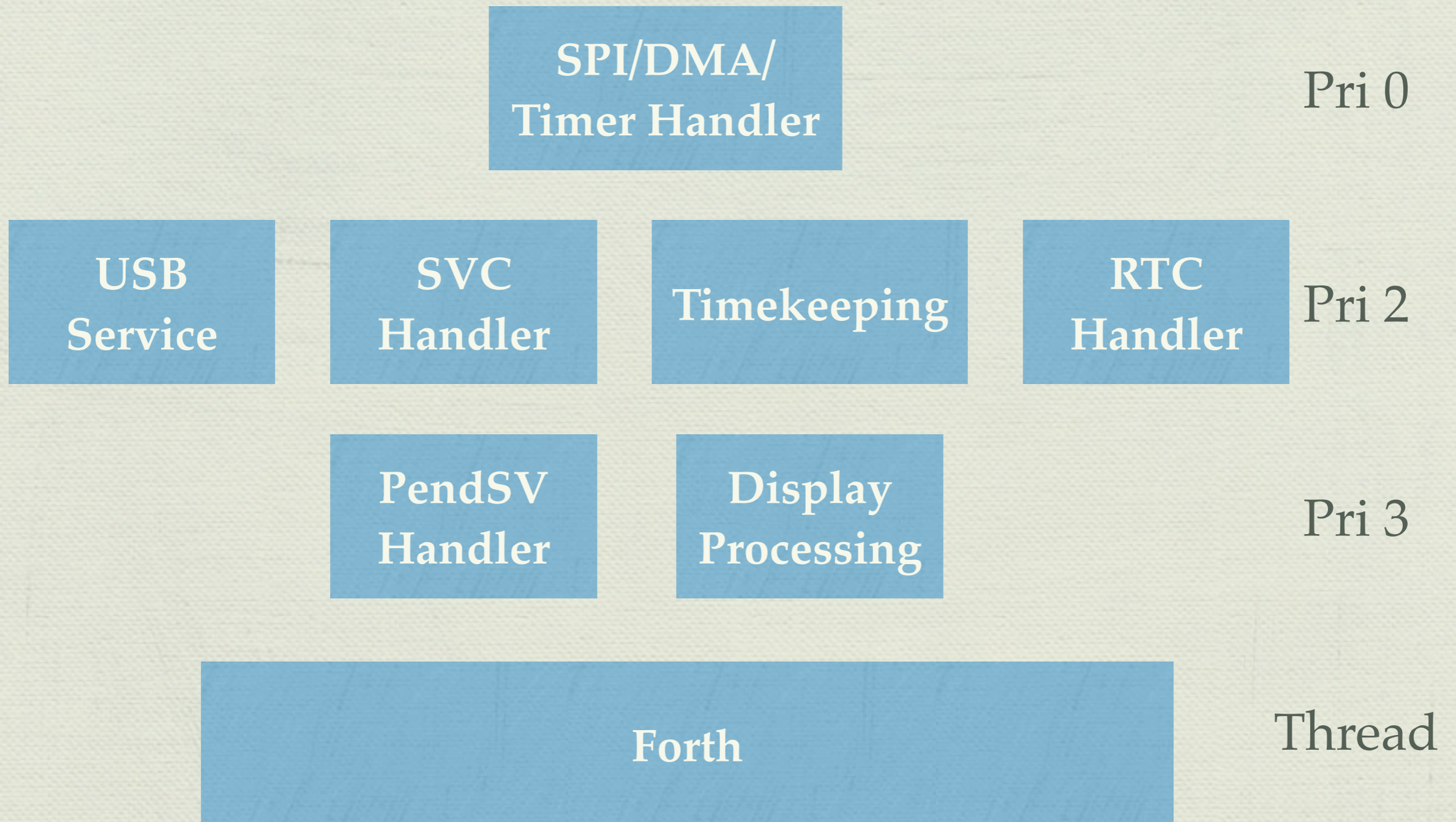
# Ambient Devices

- ◆ Invented at the MIT Media Lab
- ◆ Concept - Low Bandwidth Information
  - ◆ Weather Forecasts
  - ◆ Stock Prices
  - ◆ Mail Notification

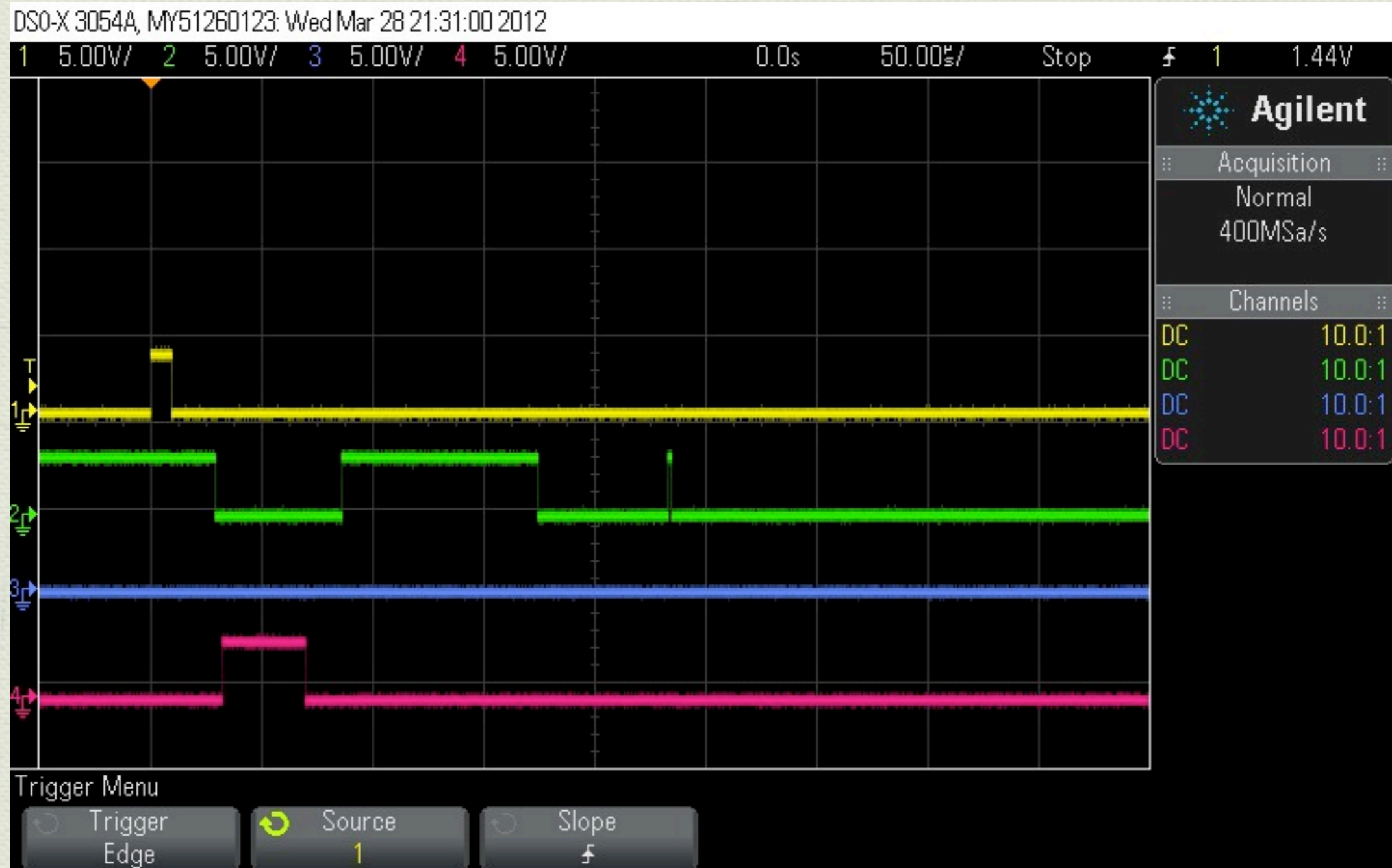
# Hardware



# Firmware Architecture



# NVIC Priority Behavior



# Power Consumption

- ◆ Exclusive of LED Power
  - ◆ 10 mA in USB Connected Mode
  - ◆ 7.7mA waiting for a connection
  - ◆ 1.5mA in suspend (131 kHz CPU)
  - ◆ Suspend / Wake Changes CPU Voltage and Frequency
- ◆ More opportunities remain for power reduction

# USB Integration

- ◆ SendChar puts an application byte into a transmission buffer
- ◆ Minimize the number of USB packets:
  - ◆ Send if there is a full USB buffer
  - ◆ Send if the buffer is old ( $> 10\text{ms}$ )
- ◆ If the transmission buffer is too full, wait for the USB interrupt handlers to drain it before returning control to the application (PendSV mechanism)



# User Interface

- ◆ USB CDC Device - Ascii Command Set
  - ◆ 60 hue, \$ffff 0 0 rgbset, etc.
  - ◆ fast pulse, slow pulse
  - ◆ extensible