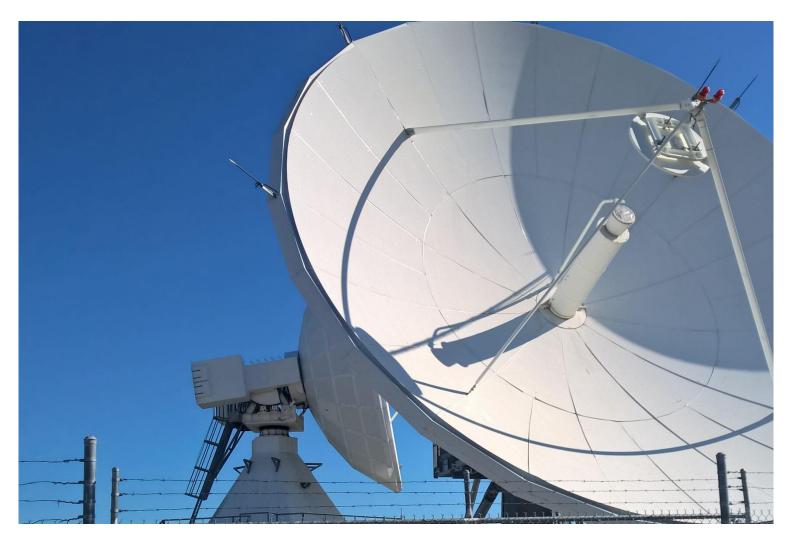
Radeus 8200 Series Antenna Controller



Earth Station 11m Antenna

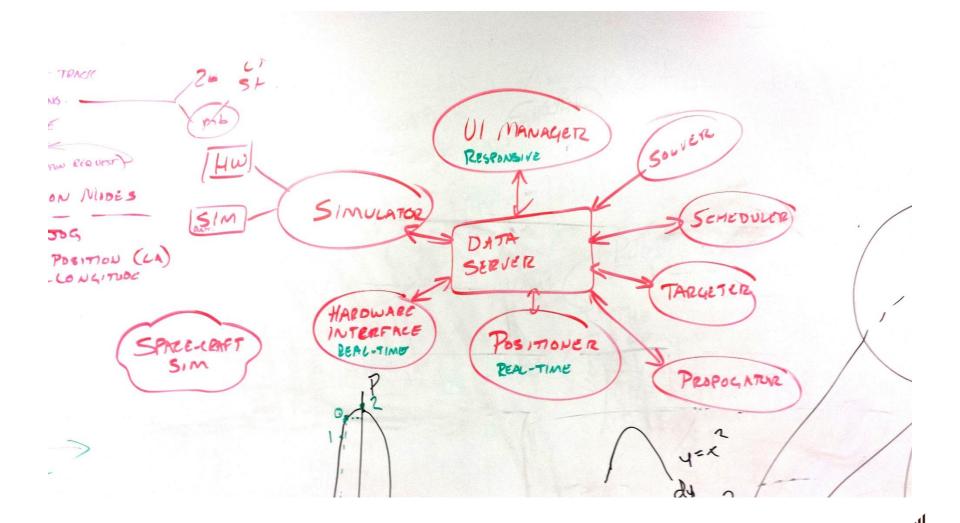


Ancient History

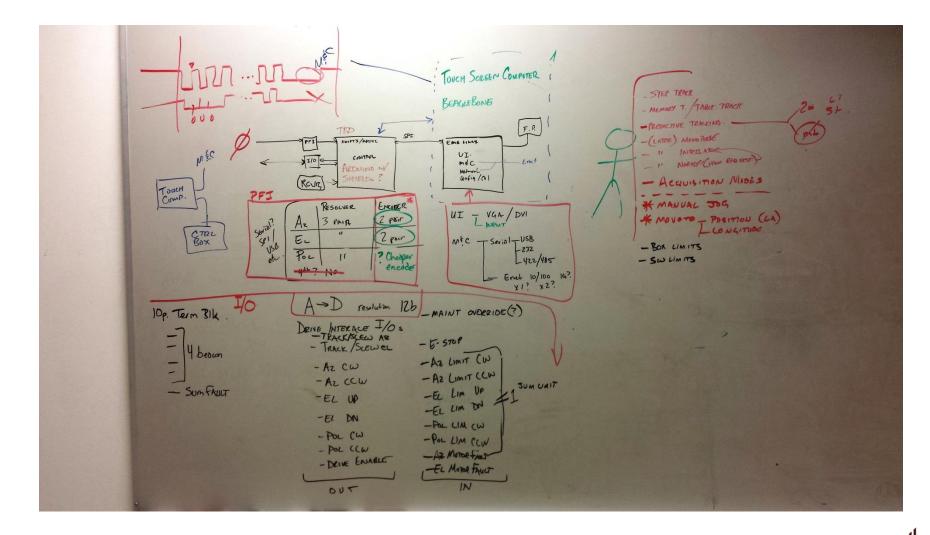


- Vertex (now General Dynamics) Model 7200
- Developed in the early 1990s
- Simple keypad/display UI

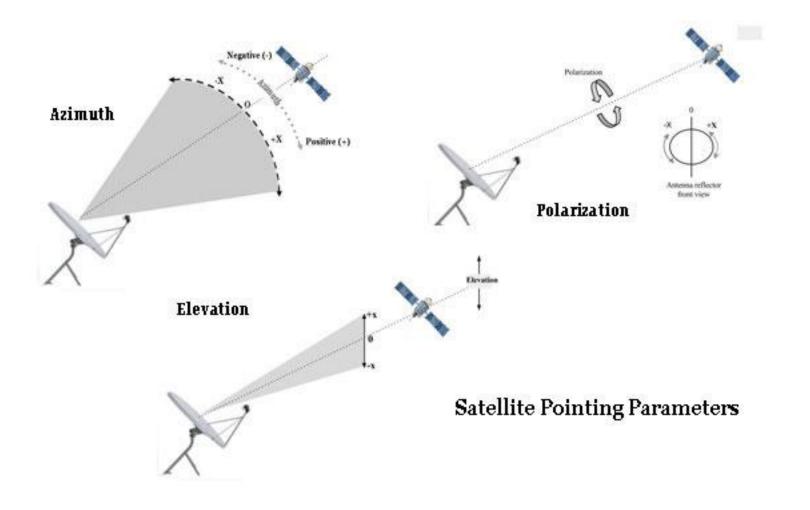
January 2015



January 2015



Antenna Axes



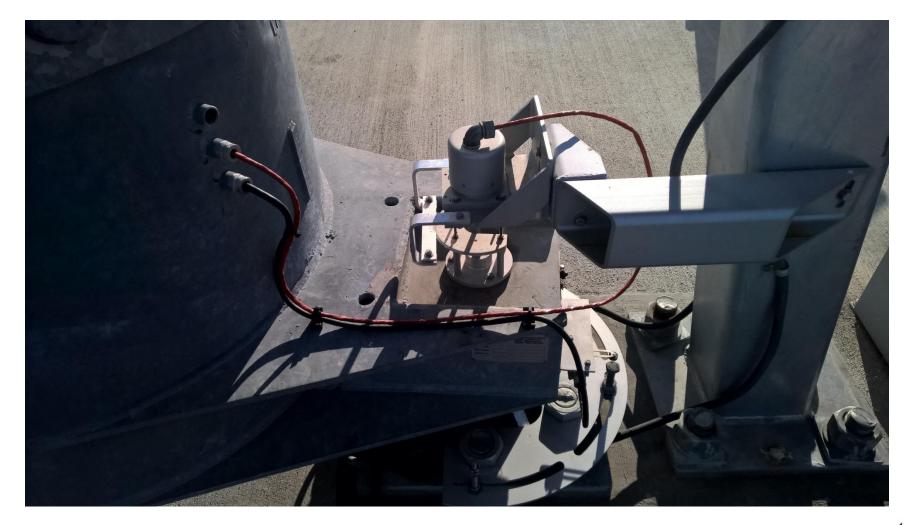


Inputs

- Azimuth Position Transducer
- Elevation Position Transducer
 - Resolver (0.01°), Optical encoder (0.001°)
- Polzarization Transducer
 - Resolver or optical (0.1°)
- Limit Switches (Both ends of each axis)
- Beacon receiver (power level in dBm)



Azimuth Position Transducer







Elevation Position Transducer



Azimuth Limit Switch







Outputs

- Azimuth Motor Controls
 - On/off, Speed (slew/track), Direction (CCW/CW)
- Elevation Motor Controls
 - On/off, Speed (slew/track), Direction (Down/Up)
- Polarizatrion Motor Controls
 - On/off, Direction (CCW/CW)
- Alarm (actually "no alarm")

Motor Controllers





Three Computers

- Transducer Interface (Encoders/Resolvers)
 - Cortex-M4, SwiftX-ARM
- Controller (positioner, fault detection)
 - Cortex-M4, SwiftX-ARM
- UI (touch-panel PC)
 - 10.2" Panel PC, Windows 7 Embedded,
 - SwiftForth, SWOOP



User Interface





Touch-Panel PC



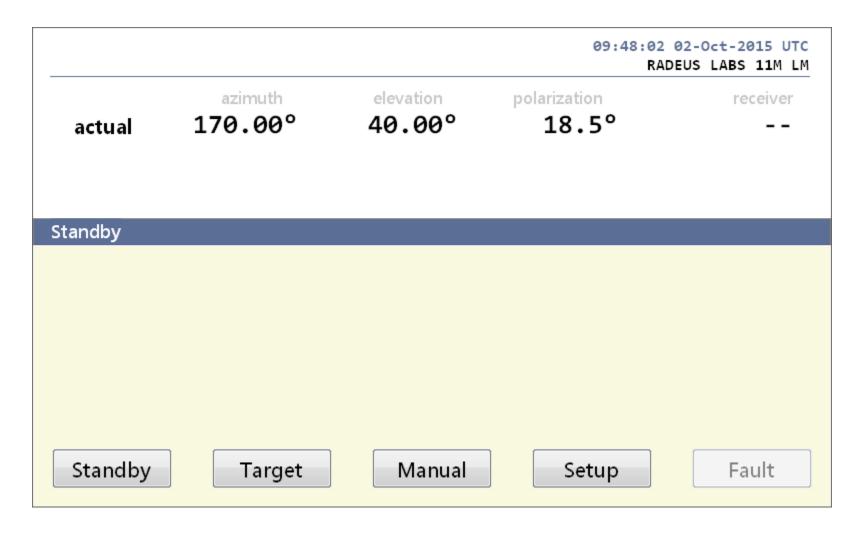


Rear Panel (Inside Chassis)



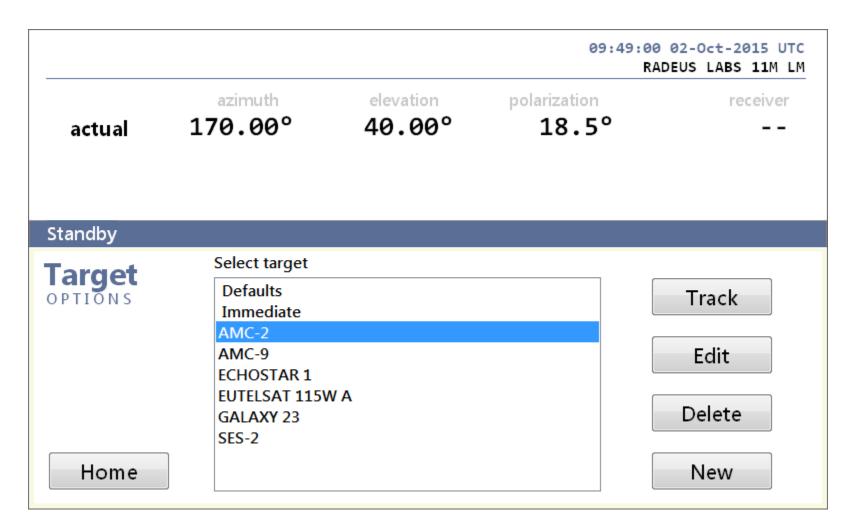


Standby





Select Target





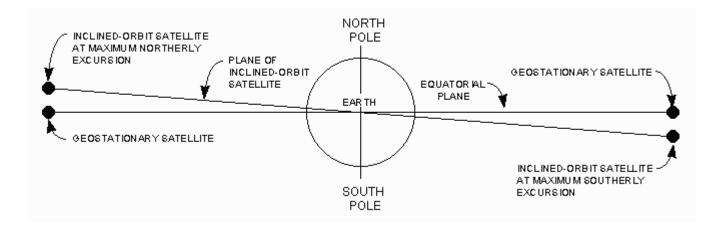


Acquire Target

				3 02-Oct-2015 UTC ADEUS LABS 11M LM
	azimuth	elevation	polarization	receiver
actual	132.68°	23.59°	42.5°	
target	132.68°	23.60°	42.5°	
Δ	0.00°	-0.01°	0.0°	
Acquiring target				
Standby	Target	Manual	Setup	Fault
			· · · ·	

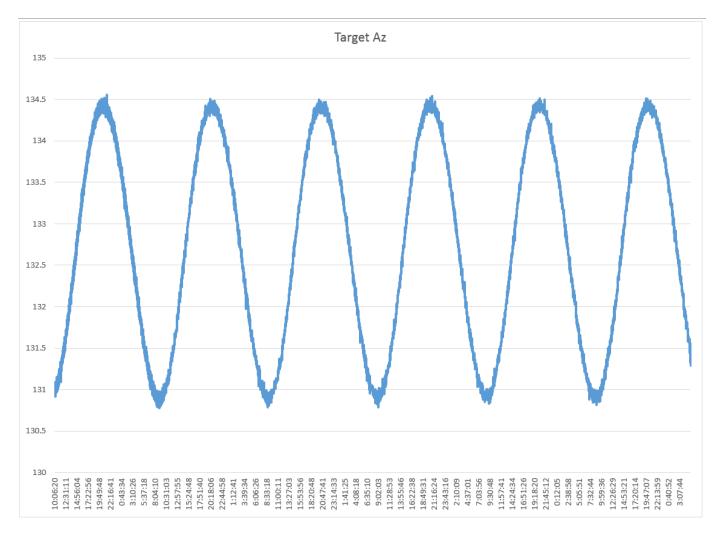


Inclined Orbit





Log Data



Test Site





